

# Design and Development of SIR based Microstrip filter for GPS Applications

M.Manoj Prabhakar,

Department of Electronics Engineering,  
Anna University, Madras Institute of Technology  
Campus,  
Chennai – 600 044, INDIA.  
E-mail : manoj.prkr89@gmail.com

M.Ganesh Madhan,

Department of Electronics Engineering,  
Anna University, Madras Institute of Technology  
Campus,  
Chennai – 600 044, INDIA.  
E-mail : mganesh@annauniv.edu

**Abstract**—A Microstrip filter for GPS L1 band (1.575 GHz) application is designed and simulated in Agilent® ADS software. The design is based on Stepped Impedance Resonator (SIR) approach. The designed filter is fabricated in FR4 substrate and an insertion loss of 7 dB and return loss of 30 dB is observed, at the required frequency .

**Keywords**—Stepped impedance resonator (SIR), micro strip filter, GPS, L1 Band, ADS.

## I. INTRODUCTION

In modern wireless and mobile communication systems, RF/microwave filters play an important role. Recently, GPS has become an essential component in many mobile communication applications [1]. This paper describes a stepped impedance resonator (SIR) approach based on non-uniform transmission line resonator, to implement a micro strip band pass filter [2]. The SIR scheme enables to achieve good harmonic suppression by making the central frequency of second band far apart from the fundamental [2]. In this study, a Microstrip Bandpass filter for GPS L1 band [3] (1.575 GHz) is designed and simulated using ADS software. The layout generated is used to develop the filter in FR4 substrate and its characteristics such as  $S_{11}$ ,  $S_{21}$ , group delay and impedance are determined.

## II. STEPPED IMPEDANCE RESONATOR

The Stepped impedance resonator (SIR) is symmetrical and has two different characteristic impedance lines,  $Z_1$  and  $Z_2$ , of admittance  $Y_1$  and  $Y_2$ . The basic structure of the  $\lambda_g/2$  SIR is shown in fig 1, where  $\lambda_g$  is the wavelength.

Whereas,  $\theta_1$  and  $\theta_2$ , are their corresponding electrical lengths. For the ease of the analysis, a new parameter  $R_z$  is introduced, which is defined as the ratio of the line impedances  $Z_1$  and  $Z_2$ , ( $R_z = Z_2/Z_1$ ).

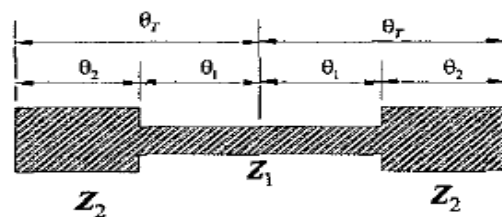


Fig. 1. Basic structure of half wavelength type SIR [2]

The resonance condition can be analyzed by using the input admittance. The input admittance of the half wavelength SIR is given as [2]

$$Y_i = jY_2 \frac{2(R_z \tan \theta_1 + \tan \theta_2)(R_z - \tan \theta_1 \tan \theta_2)}{R_z(1 - (\tan \theta_1)^2)(1 - (\tan \theta_2)^2) - 2(1 - R_z^2) \tan \theta_1 \tan \theta_2} \quad (1)$$

The resonance condition is achieved at  $Y_i = 0$ , and this is realized by the following equation

$$(R_z \tan \theta_1 + \tan \theta_2)(R_z - \tan \theta_1 \tan \theta_2) = 0 \quad (2)$$

If we assume  $\theta_1 = \theta_2 = \theta_0$ , equation (2) can be rewritten as

$$(R_z \tan \theta_0 + \tan \theta_0)(R_z - (\tan \theta_0)^2) = 0 \quad (3)$$

From (3), we obtain the following solution,

$$\theta_0 = \tan^{-1} \sqrt{R_z} \quad (4)$$

The relationship between fundamental and spurious frequencies is given by [1]

$$\frac{f_{SB1}}{f_0} = \frac{\theta_{s1}}{\theta_0} = \frac{\pi}{2 \tan^{-1} \sqrt{R_z}}$$

$$\frac{f_{SB2}}{f_0} = \frac{\theta_{s2}}{\theta_0} = 2 \left( \frac{f_{SB1}}{f_0} \right) - 1$$

$$\frac{f_{SB3}}{f_0} = \frac{\theta_{s3}}{\theta_0} = 2 \left( \frac{f_{SB1}}{f_0} \right) \quad (5)$$

Thus the spurious frequencies can be controlled by impedance ratio  $R_z$ .

### III. FILTER SCHEMATIC AND DESIGN

A filter with a second order Chebychev response is considered for the design. By taking  $\frac{f_{SB1}}{f_0} = 2.5$  [2], hence, the value of  $R_z$  is obtained as 0.5. From the value of  $R_z$ , and considering  $Z_2 = 50 \Omega$ , then  $Z_1$  is obtained as  $100 \Omega$ .

in the fig. 5. The 20dB bandwidth of the filter is found to be 230 MHz (Fig. 6).

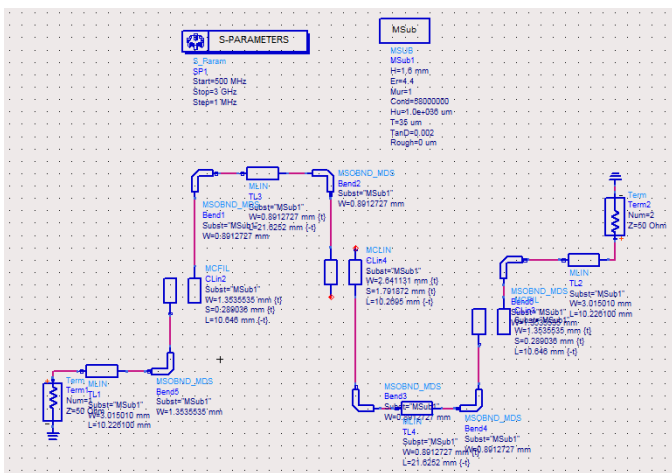


Fig. 2. Schematic of the filter

The filter is implemented in FR4 substrate with dielectric thickness 1.6 mm, dielectric constant 4.4 and conductor thickness of 0.035 mm. The filter is simulated in ADS tool. Fig 2 shows the schematic of the filter in ADS.

The layout corresponding to the filter schematic is obtained in ADS, and shown in Fig.3. In the layout, the dark areas denote the conducting strip and background denotes the substrate.

### IV. RESULTS AND DISCUSSION

The layout is simulated in ADS- Momentum and the S parameter characteristics are obtained as shown figure 4. The insertion loss in the pass band is found to be 1.013 dB. The return loss ( $S_{11}$ ) in the pass band is obtained as 21.137 dB.

From the  $S_{21}$  characteristics, The 3 dB bandwidth of the filter is calculated around 60 MHz. The response is shown

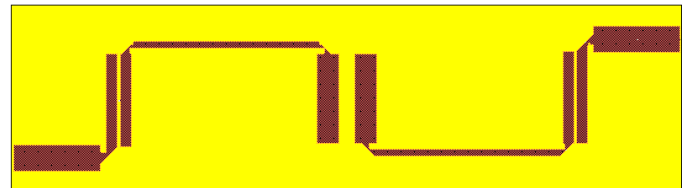


Fig.3. Layout of the filter

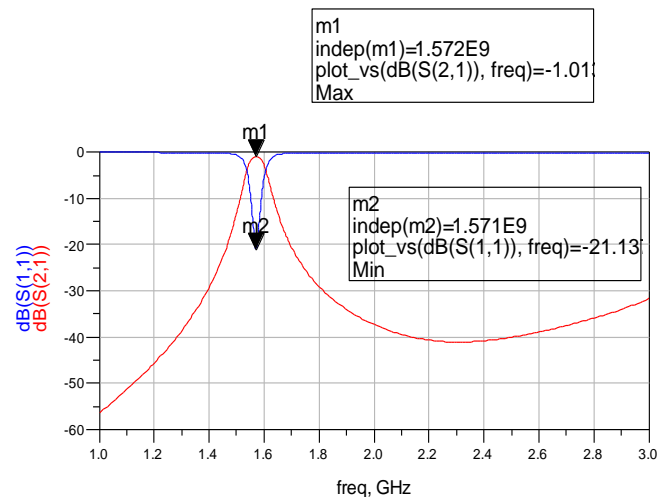


Fig.4. S-parameter characteristics

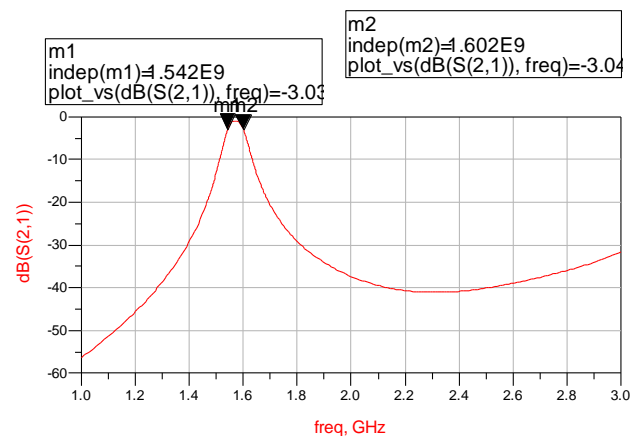


Fig.5. 3 dB bandwidth

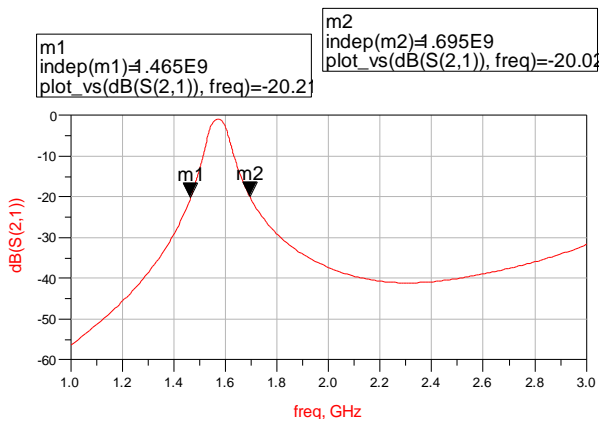


Fig. 6. 20 dB bandwidth

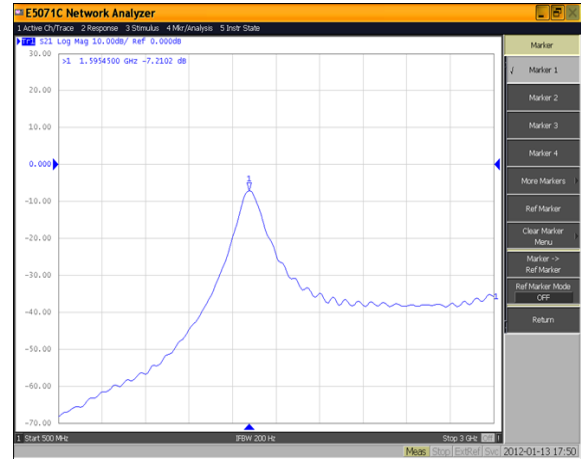


Fig.8. Measured  $S_{21}$  response

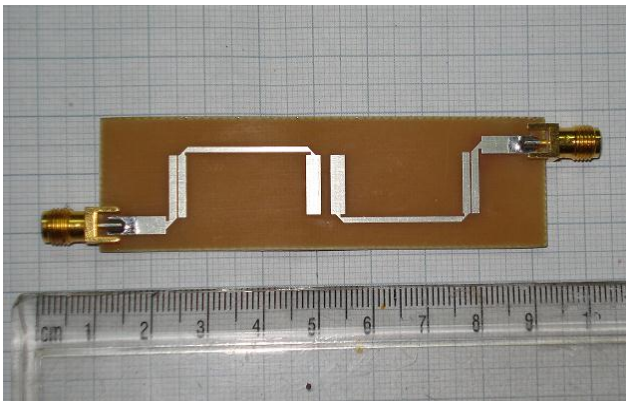


Fig.7. Photograph of the fabricated filter

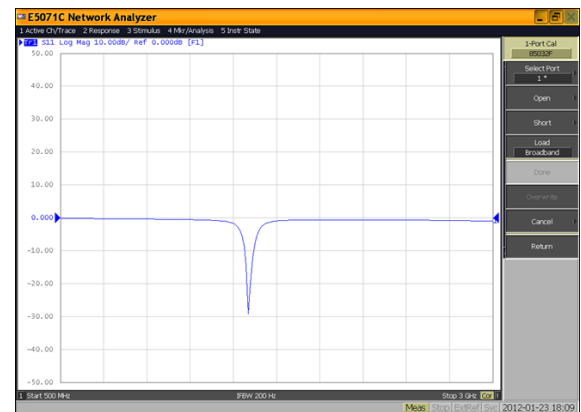


Fig.9. Measured  $S_{11}$  response

The photograph of the fabricated filter is shown in fig.7. An Agilent E5071C Network analyzer (8 GHz) is used to measure the filter characteristics. The measured  $S_{21}$  and  $S_{11}$  response of the filter are shown in fig.8 and fig.9 respectively. The insertion loss is found to be 7dB. The return loss is found to be 30 dB. A higher value of insertion loss is seen in the measurement owing to the non uniformities of the substrate material. Fig.10 shows the group delay of the filter which is almost constant around 5.6 ns, in the pass band.

The impedance and SWR of the filter is shown in fig.11 and fig.12 respectively. They indicate an SWR value of 1.2 and impedance value of 48.5 Ohms. These values are close to the ideal values and will lead to better filter performance.

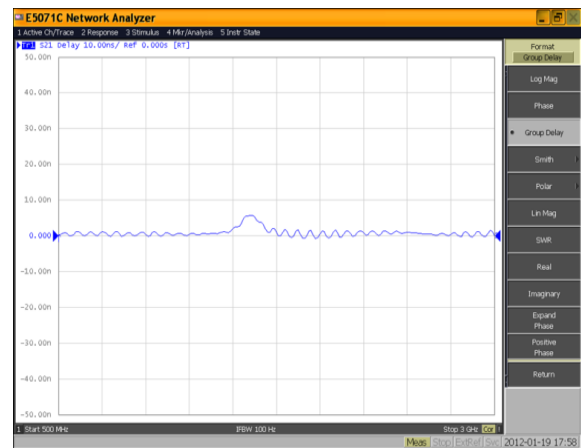


Fig.10. Measured Group Delay of the filter.

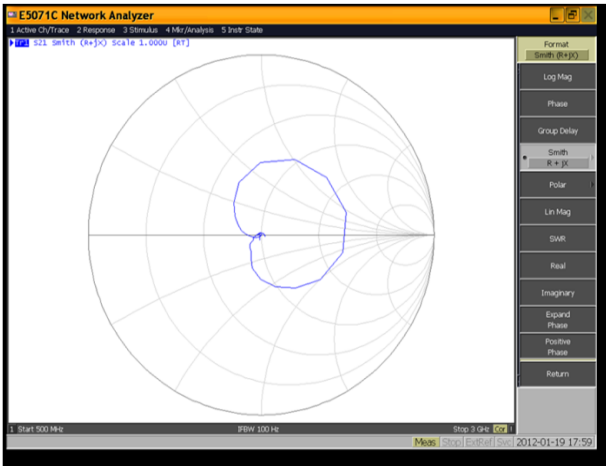


Fig.11. Measured Impedance of the filter

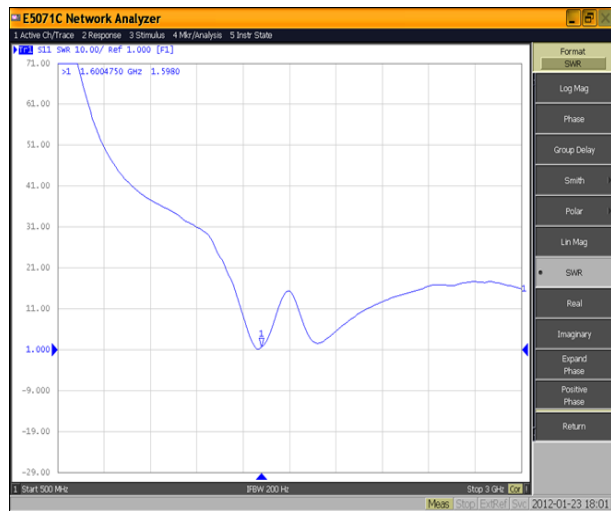


Fig.12. Measured SWR of the filter.

## REFERENCES

- [1] James Bao-Yea Tusi, "Fundamentals of Global Positioning System Receivers: A Software Approach", Second Edition, © John Wiley & Sons 2005
- [2] M.Makimoto and S.Yamashita, "Microwave Resonator and Filters for Wireless Communication, Theory Design and Application", Springer 2001.
- [3] Alkan, R.M.; Karaman, H.; Sahin, M.; "GPS, GALILEO and GLONASS satellite navigation systems & GPS modernization" Proceedings of 2nd International Conference, Recent Advances in Space Technologies, 2005. Page(s):390 - 394

## V. CONCLUSION

A method of designing a BPF suitable for GPS L1 band with SIR is established, and a microstrip bandpass filter using stepped-impedance resonator has been proposed, designed and fabricated. Measurement shows an insertion loss of 30 dB, impedance of 48 Ohms and SWR of 1.2 at the desired frequency.